

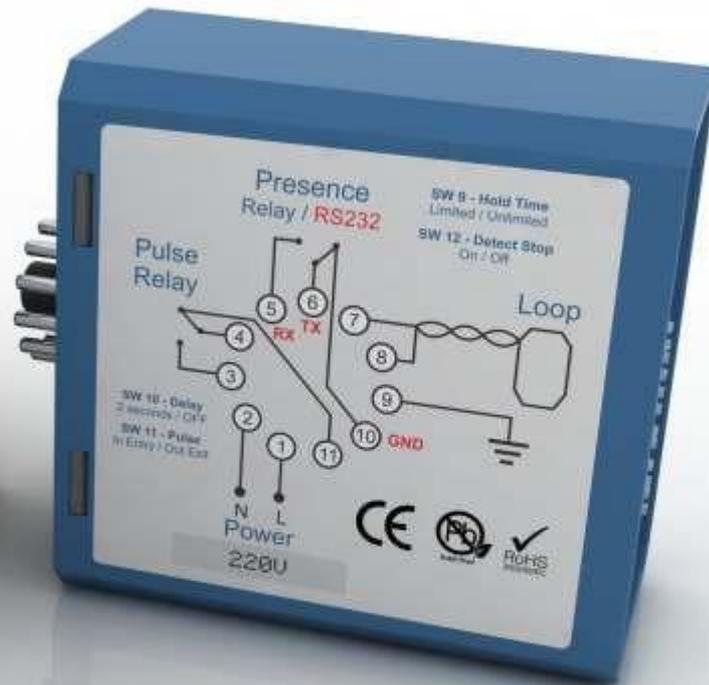
# INSTRUCTION MANUAL



Vehicle Loop Detector

# PD-182





PD-182 Vehicle Loop Detector



Chapter

1

# DipSwitch Settings

How to setup all functions  
from PD-182

## In this chapter you can see



- ✓ Frequency Selection - 4 levels [page...5](#)

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- ✓ Sensitivity Selection - 8 levels [page...6](#)

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- ✓ ASB - Automatic Sensitivity Boost [page...7](#)

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- ✓ Signal Filtering [page...8](#)

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- ✓ Pulse Mode / Delay [page...10](#)

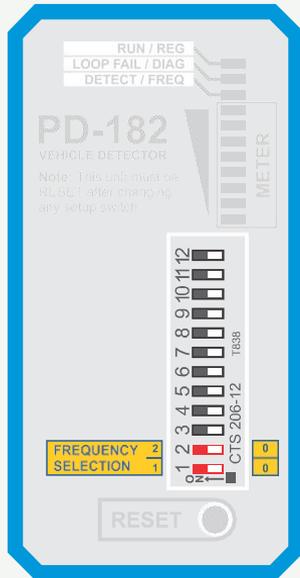
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- ✓ Detect Stop [page...11](#)

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## Frequency Selection - 4 levels



The operating frequency of the loop is a function of the specific loop inductance and DIP switch settings 1-2. The primary purpose of the frequency setting is to allow the installer the ability to set different operating frequencies for multi-loop installations, recommended to prevent crosstalk/interference from adjacent loops. After changing the frequency setting, the detector will re-initialize and show the new operating frequency.



Frequency LOW



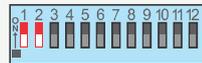
Frequency MID  
LOW



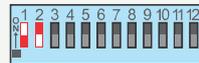
Frequency MID HIGH



Frequency HIGH



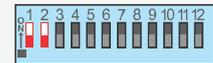
DipSwitch 1 and 2 is OFF



DipSwitch 1 is  
ON



DipSwitch 2 is  
ON



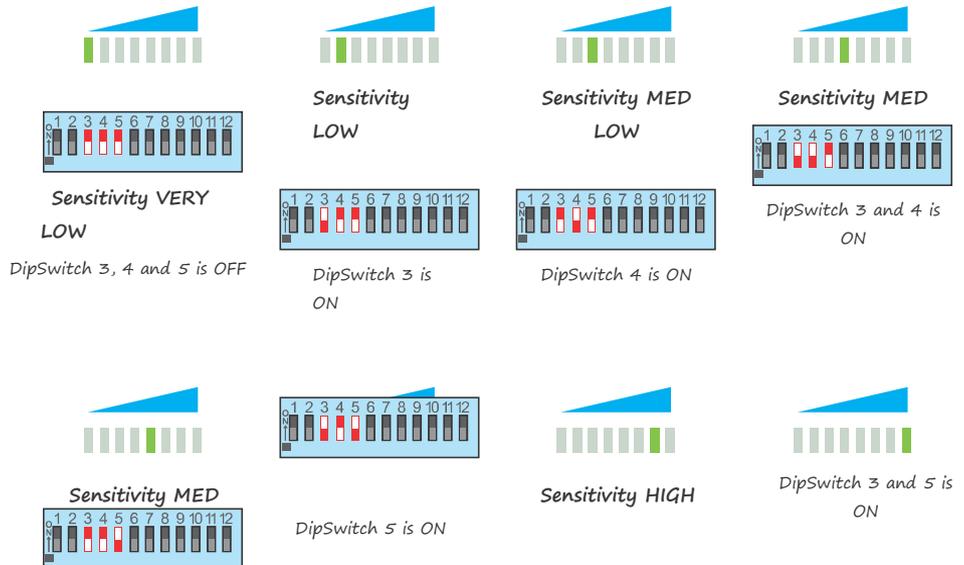
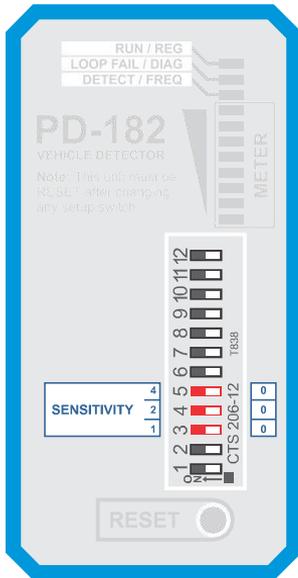
DipSwitch 1 and 2 is  
ON





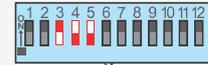
## Sensitivity Selection - 8 levels

The Sensitivity is the minimum change in inductance required to produce a detect output. Eight Sensitivity settings are available on the switches to allow flexibility in configuration. Typical applications require a setting of 3 or 4.



Sensitivity **VERY HIGH**

DipSwitch 4 and 5 is  
ON



**MAXIMUM**

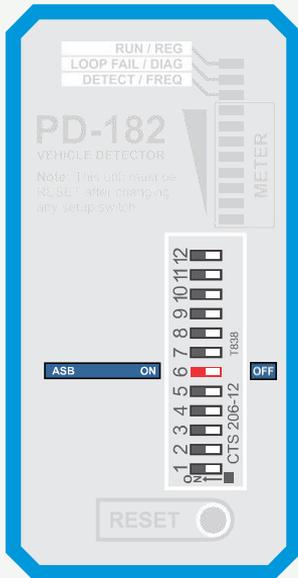


DipSwitch 3, 4 and 5 is  
ON

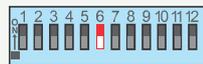


## ASB - Automatic Sensitivity Boost

The Automatic Sensitivity boost causes the sensitivity to increase following initial detection. This feature is useful to prevent dropout when detecting high-bed vehicles. The sensitivity returns to its normal setting after the vehicle exits the loop.



**ASB activated**  
DipSwitch 6 is ON



**ASB deactivated**  
DipSwitch 6 is OFF

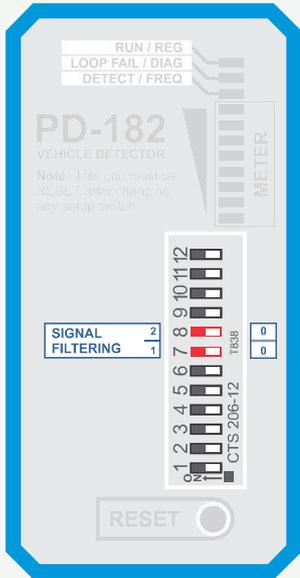






# Signal Filtering

This feature inputs a momentary delay into the detection circuit to verify that a vehicle is present in the loop for a minimum time period before activation occurs. In some applications it is necessary to filter out short detections such as cross traffic or short burst of radio frequency interference.



Signal Filtering LOW  
DipSwitch 7 and 8 is OFF



Signal Filtering MID LOW  
DipSwitch 7 is ON



Signal Filtering MID HIGH  
DipSwitch 8 is ON



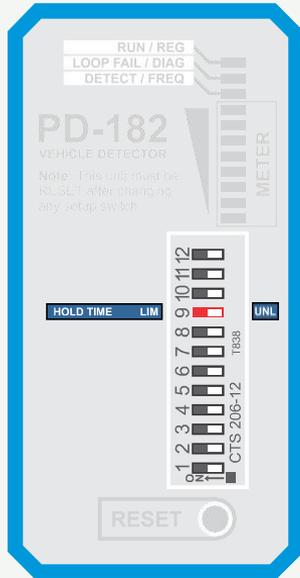
Signal Filtering HIGH





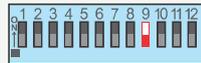


## Hold Time



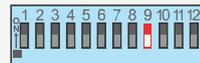
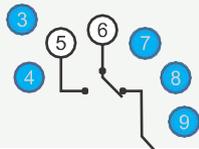
This feature allows for the detector to hold the Presence Relay for as long as any vehicle is in the detection loop or to allow the Presence Relay to de-activate after 10 minutes.

**Warning !** DO NOT USE hold time function unless opening is protected by a secondary safety device.



*Hold Time Limited*

*DipSwitch 9 is ON*



*Hold Time Infinite*

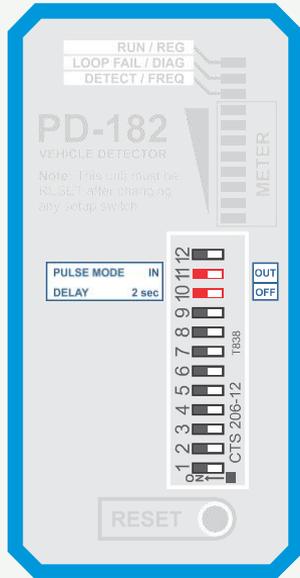
*DipSwitch 9 is OFF*



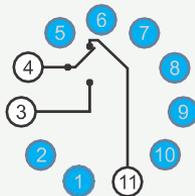




## Pulse Mode / Delay



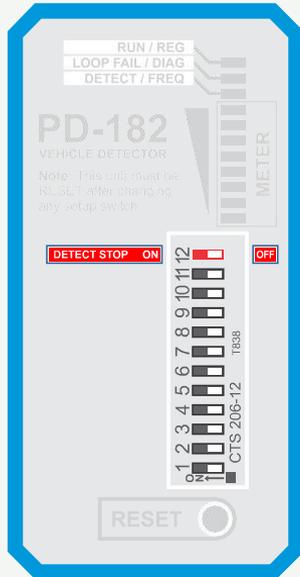
Pulse function is provided by the Relay Output on pins 3, 4, and 11. The pulse of about 0.5 second can be generated when the car enters the loop or when it exits with option of 2 seconds delay.



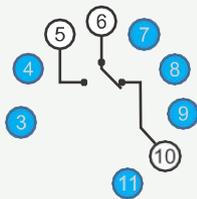




## Detect Stop

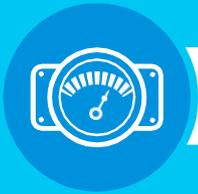


The Detect Stop feature requires that a Vehicle must come to a complete stop over the loop for a minimum of 1 second (typical 1-2s) before activates Relay Output on pins 5, 6, and 10.



DETECT AFTER 1-2 sec





Chapter

2

## LED Panel Indications

How to read all LED Panel  
Indications from PD-182

## In this chapter you can see



- ✓ Run / Fail Memory / Serial Connection [page...14](#)

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- ✓ Level Meter [page...15](#)

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- ✓ Loop Fail / Diagnostics / Recalibration [page...16](#)

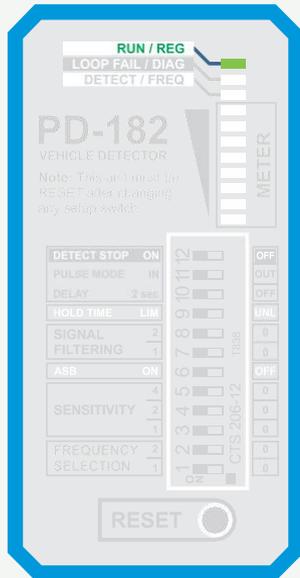
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- ✓ Detection / Frequency Counter [page...17](#)

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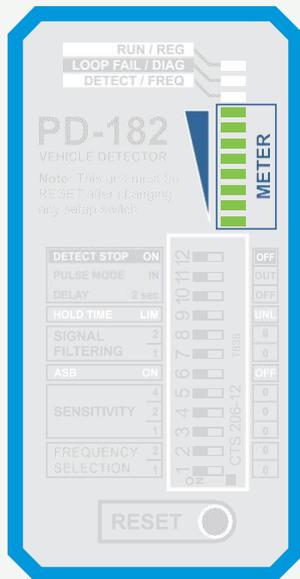
## Run/Fail Memory/Serial Connection



Indication	Possible cause	Solution
Green LED flash fast	Working	Nothing to do
Green LED is ON	Detector is connected using RS232 protocol	Nothing to do
Green LED flash slow	Loop was previously shorted or open	Check loop resistance on the appropriate loop pins on the control board connector. Press RESET to clear this indication.



## Level Meter

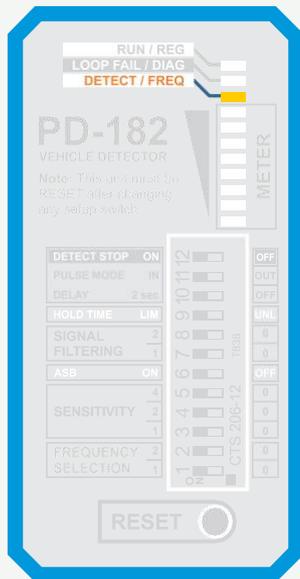


Indication	Possible cause	Solution
After Reset one LED from Meter is ON	Sensitivity Level Indication	Nothing to do
Meter is Instable	<ol style="list-style-type: none"> <li>1 - Faulty loop</li> <li>2. Poorly crimped terminals</li> <li>3. Loose connections</li> <li>4. Cross-talk between adjacent loops</li> </ol>	<ol style="list-style-type: none"> <li>1. Perform megger test from loop lead to ground, should be &gt;100 mega ohms</li> <li>2. Check loop connections to terminals</li> <li>3. Check splices are properly soldered and sealed against moisture</li> <li>4. Set adjacent loops to different frequencies (see Frequency Setting)</li> </ol>
Level remains full after vehicle has left loop	Loop sensitivity set too low	Increasing the sensitivity using the DipSwitch 3, 4 and 5





## Detection / Frequency Counter



Indication	Possible cause	Solution
With vehicle on loop LED is ON	Detection event	Nothing to do
After change the DipSwitch 1 or 2 LED start flash	Frequency Counter Function	Loop oscillator frequency is displayed on yellow status LED after the device is reset. LED will flash in steps of 10 kHz. Example: If LED flash 7 times it means that the frequency of loop is from 70 kHz to 79 kHz.



Chapter

3

## Pin Out Description

How to connect all  
pins from PD-182

## In this chapter you can see



✓ 11 Output Pins

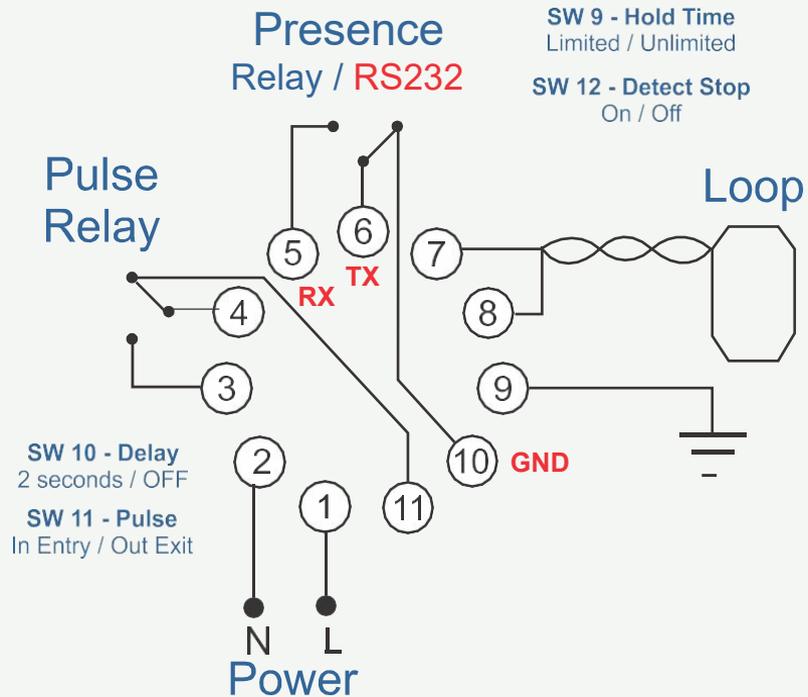
[page 20](#)

✓ Socket

[page 21](#)



## 11 Output Pins





## Socket



Pin	Values
1	220 VAC
2	220 VAC, Neutral
3	Pulse Relay NO Contact
4	Pulse Relay NC Contact
5	Presence Relay Common
6	Presence Relay NO Contact
7	Loop Wire
8	Loop Wire
9	--
10	--
11	Presence Relay NC Contact



Chapter

4

# Technical Features

Specifications about PD182



## Technical Features

Specifications	Values
<b>Loop Frequency</b>	4 settings (low, med-low, med-hi, high)
<b>Loop Inductance</b>	20...2000 $\mu$ H (Q factor > 5)
<b>Frequency Range</b>	40 kHz – 140 kHz
<b>Sensitivity</b>	0.001 % - 0.5% digital in 8 steps
<b>Level Meter</b>	Indicates sensitivity level, detection level and interference
<b>Grounded loop</b>	Isolation transformer allows operation with poor quality
<b>Automatic tuning</b>	Detector tunes to loop on power-up
<b>Environmental tracking</b>	Automatic compensation
<b>Surge protection</b>	Loop circuitry protected by surge suppressors
<b>Presence relay / Pulse relay</b>	SPDT relay contacts (form C)
<b>Contact rating (resistive load)</b>	2A @ 30VDC, 0.5A @ 125VAC
<b>Detect Stop</b>	Requires vehicle to stop for a minimum of 1 second
<b>ASB (Automatic Sensitivity Boost)</b>	Increases sensitivity after initial detection
<b>Detection speed</b>	<10 ms (at LOW filtering stage and at loop frequency of 40 kHz)
<b>Detection type</b>	Detect Presence / Detect Stop / Pulse 0.5 sec / Delay pulse
<b>Power</b>	12 /24VAC/ DC or 110V,200V ,240 VAC (48...62Hz) (Max. 1.4 VA)
<b>Operating temperature</b>	-40°C...82°C (-40°F...180°F) 0...95% relative humidity
<b>Enclosure</b>	73mm (2.9") x 38mm (1.2") x 78mm (3.1") - 0.25 lbs. (113 g) - IP30
<b>Connector</b>	11 pin male connector (JEDEC B11-88)